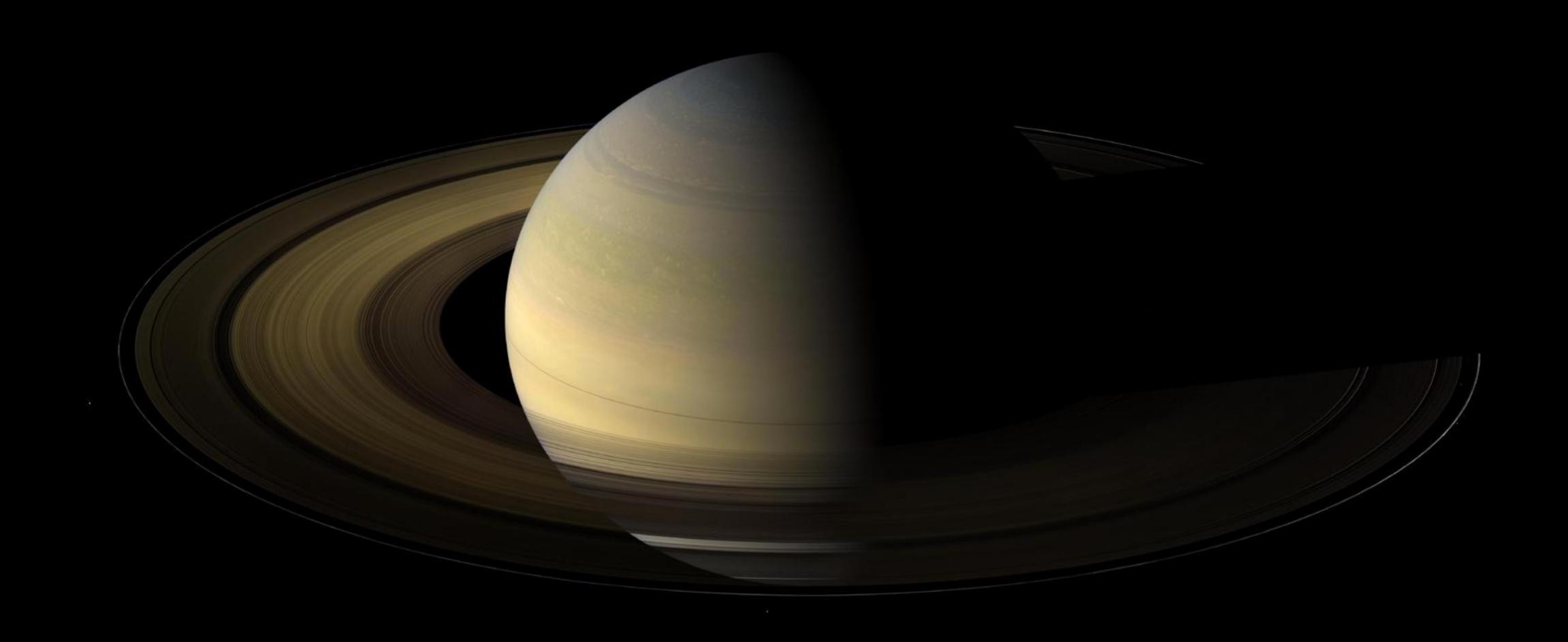
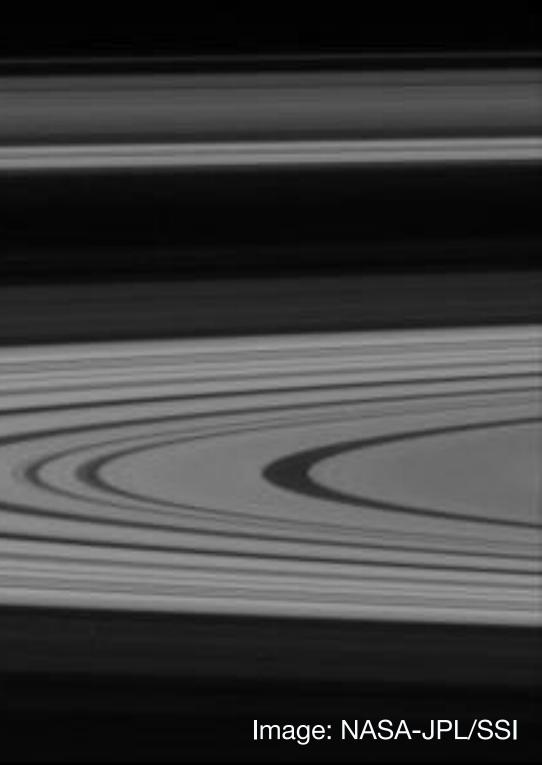
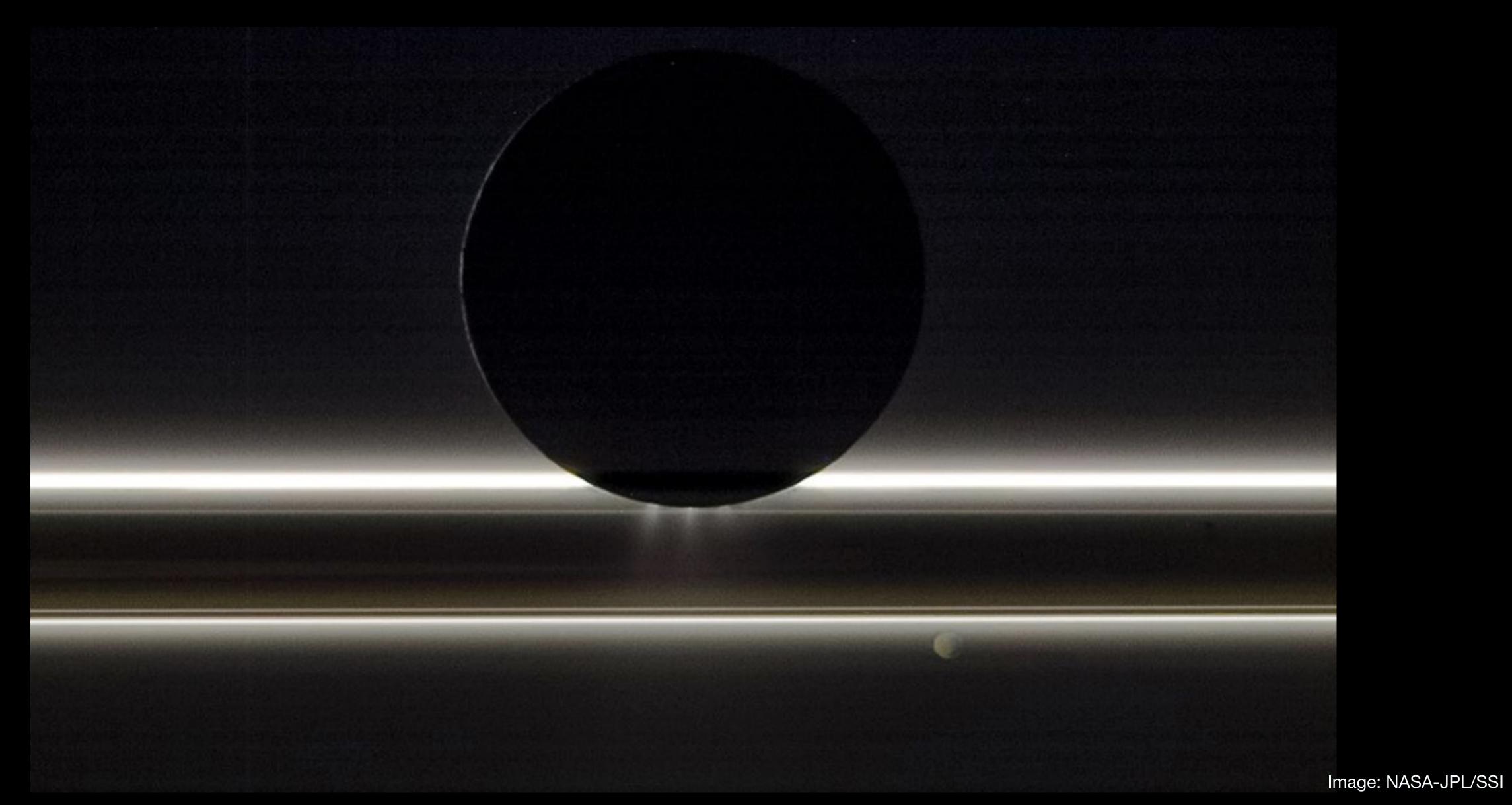
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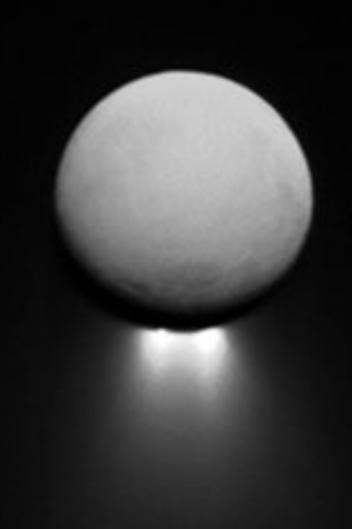
#### **EELS Mission Concept Special Presentation**

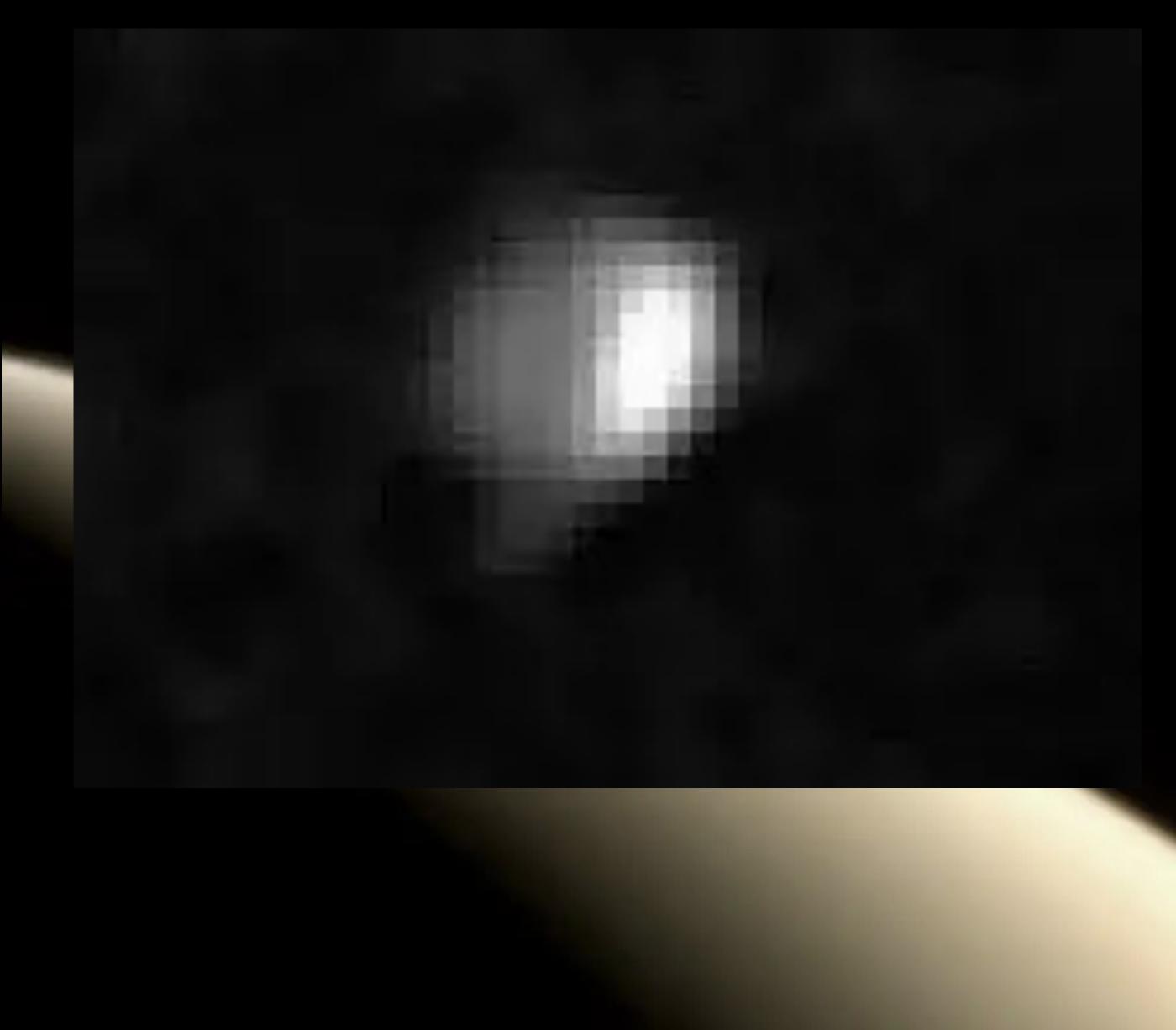


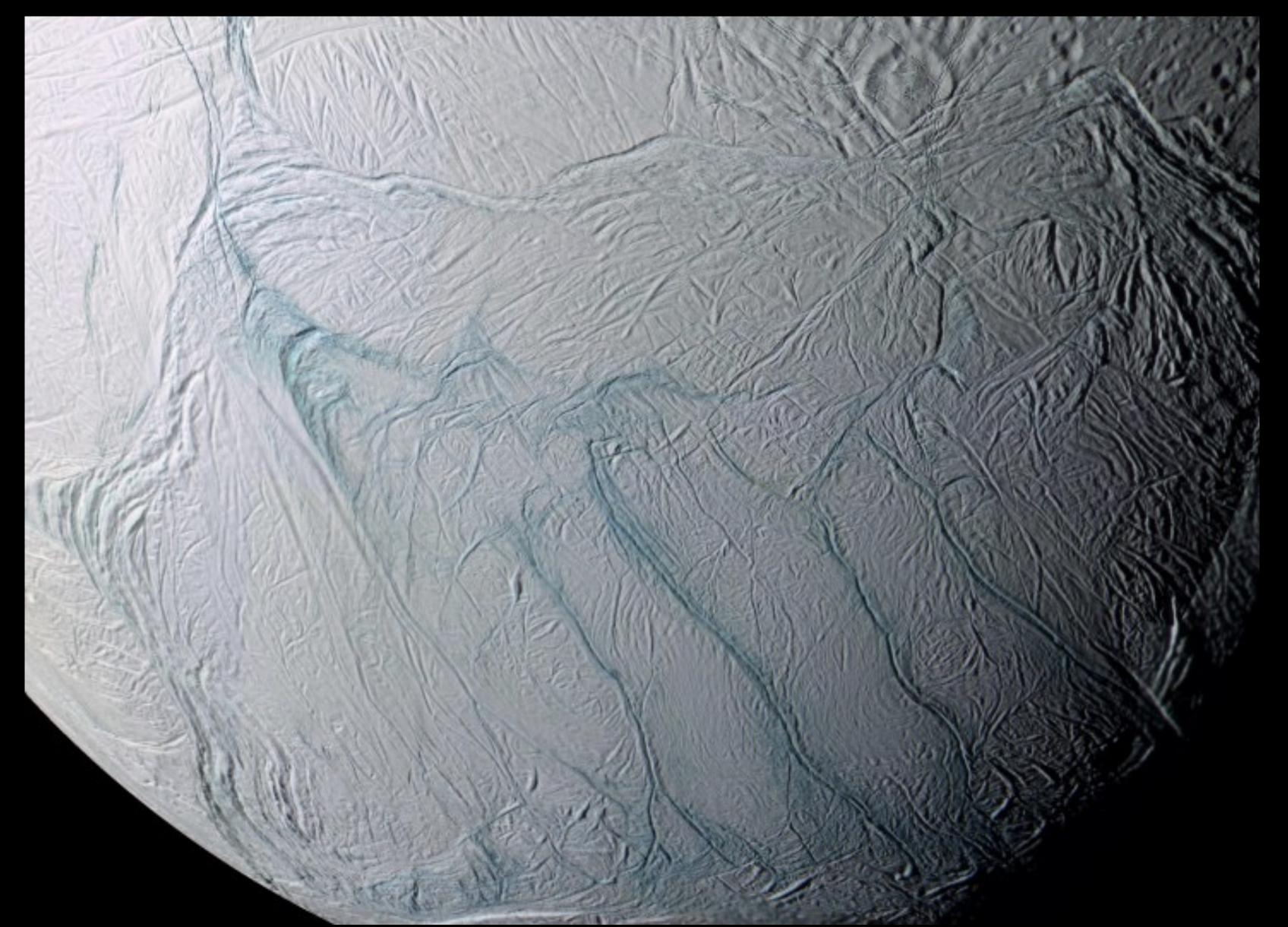


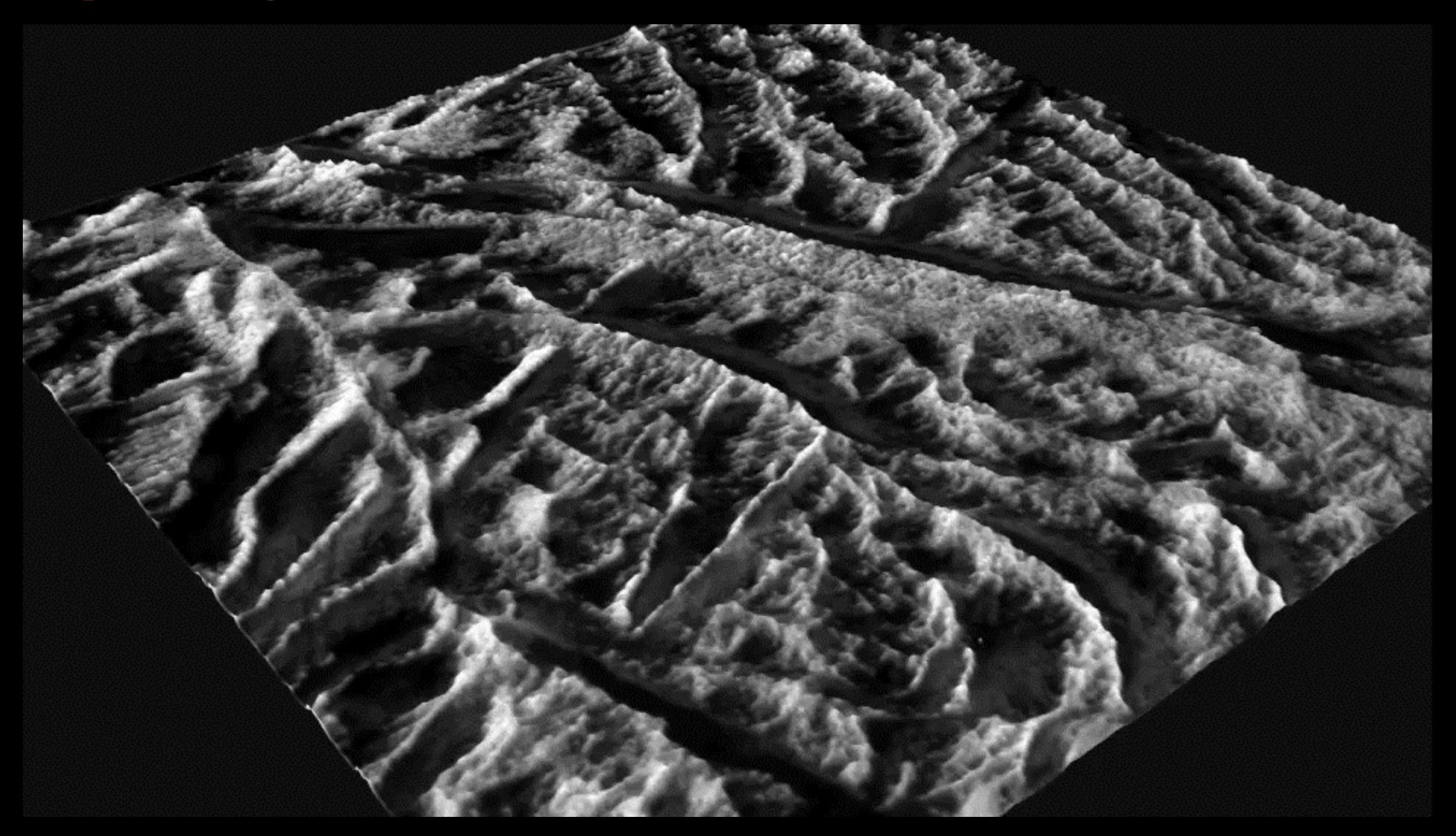


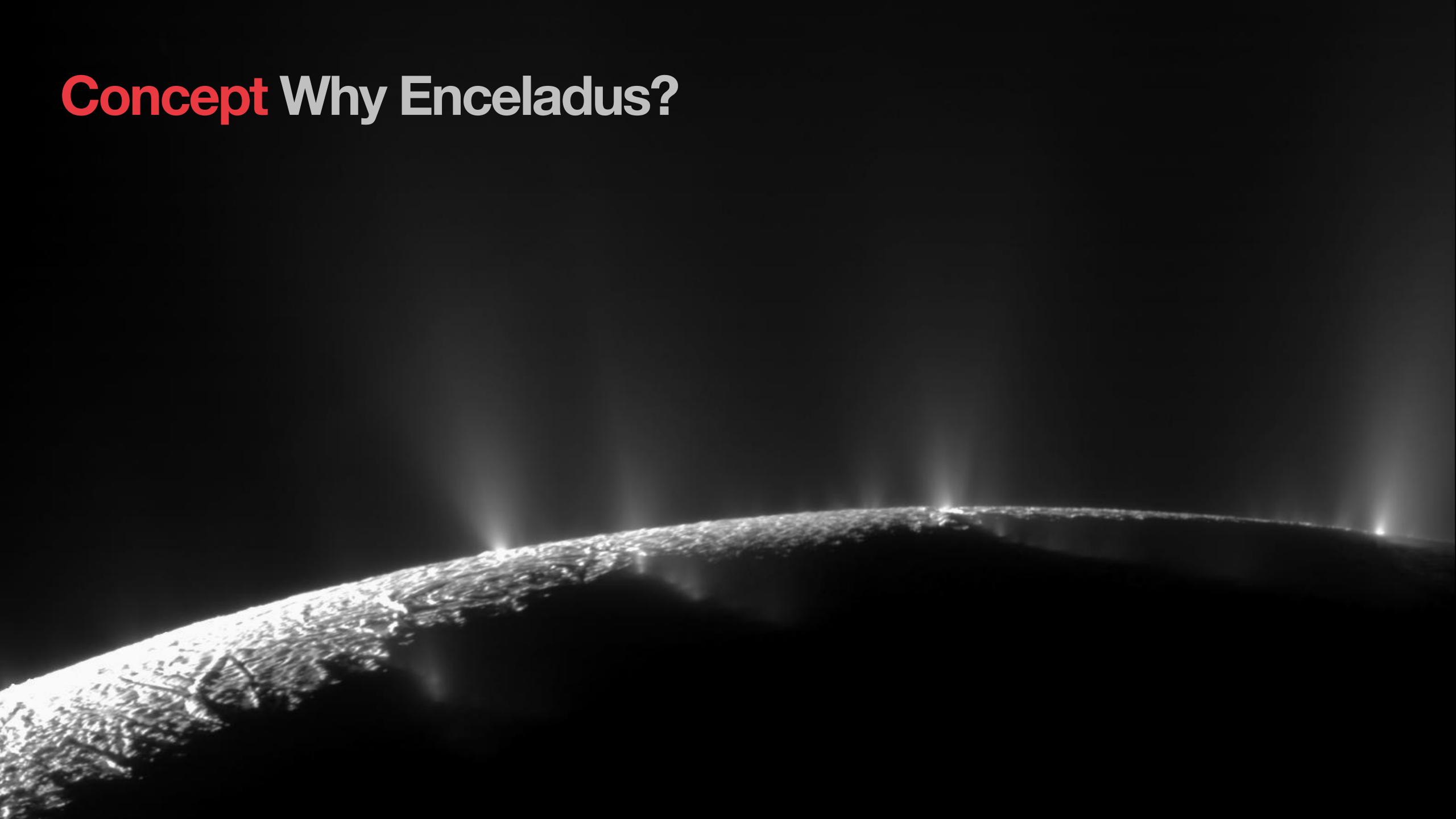


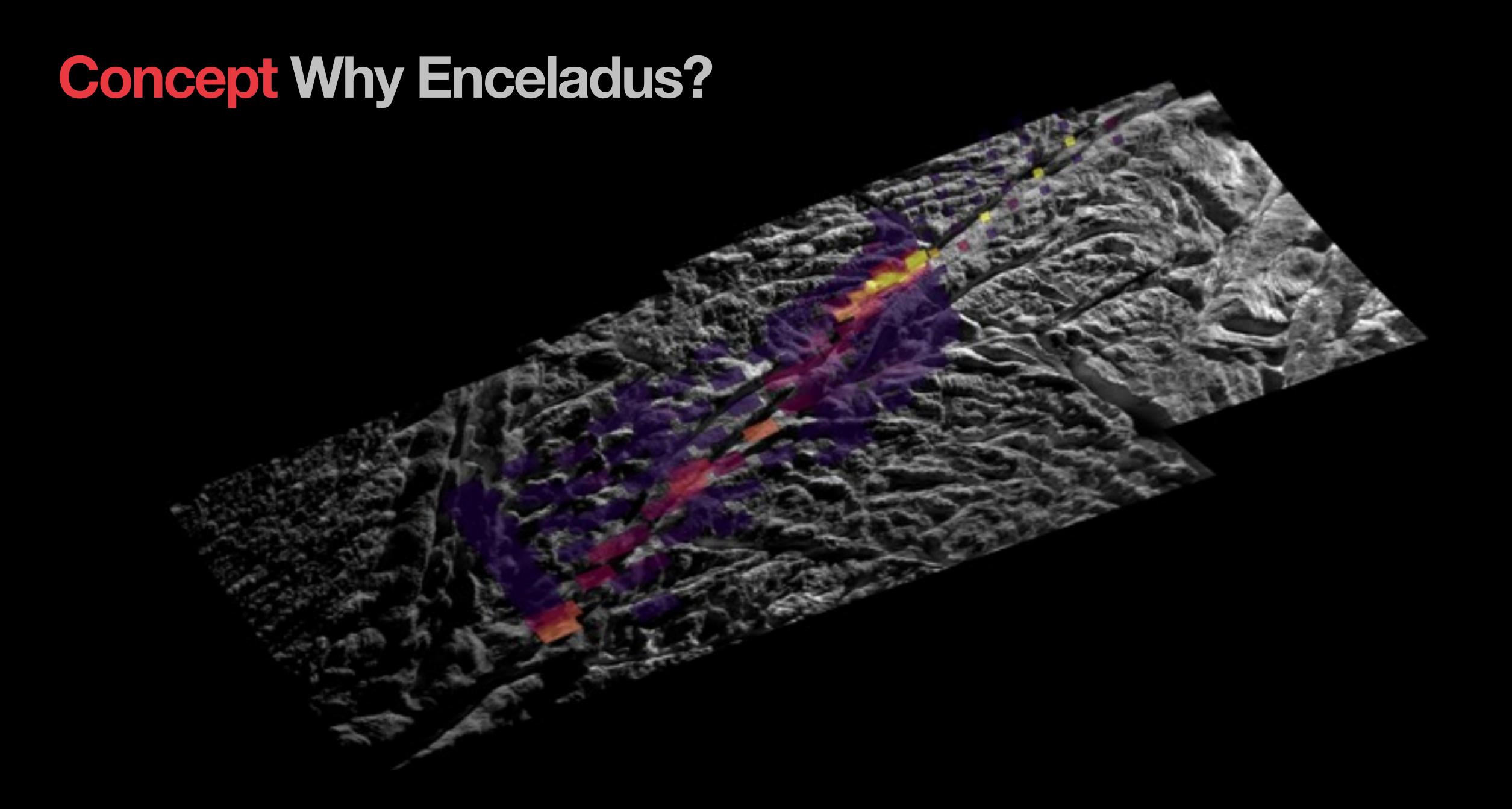


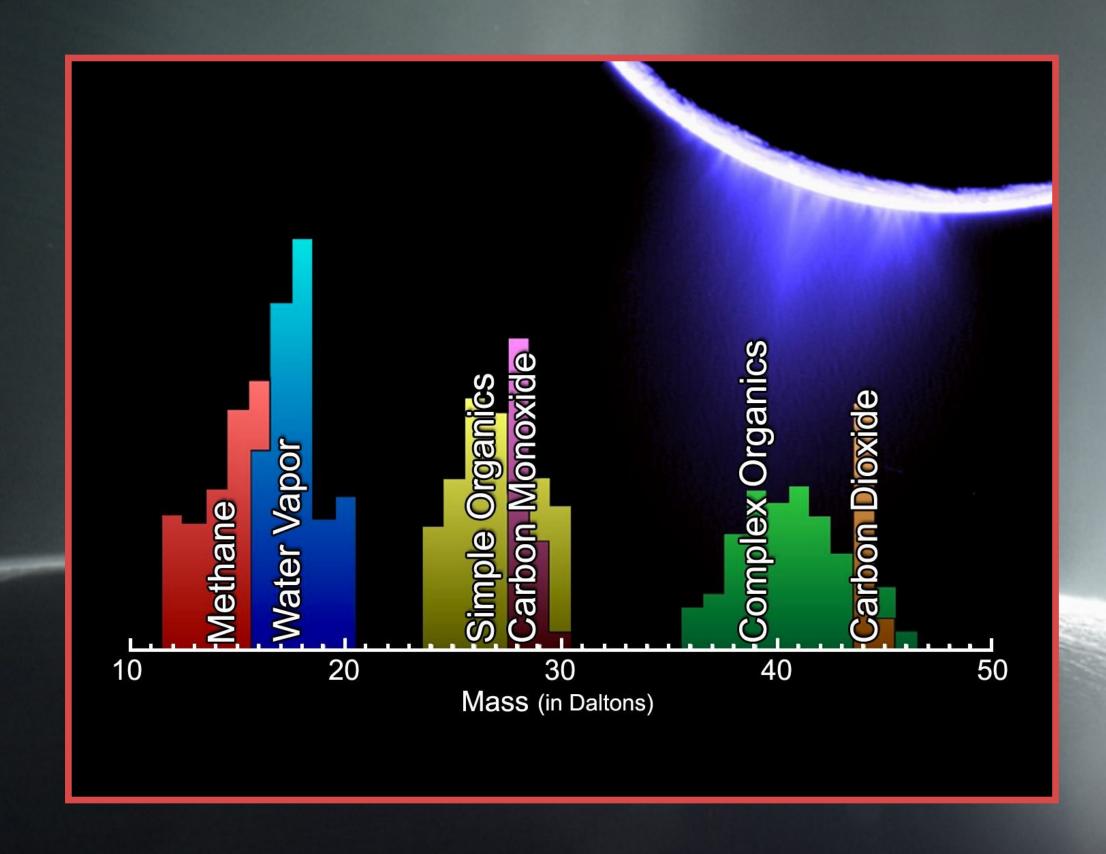


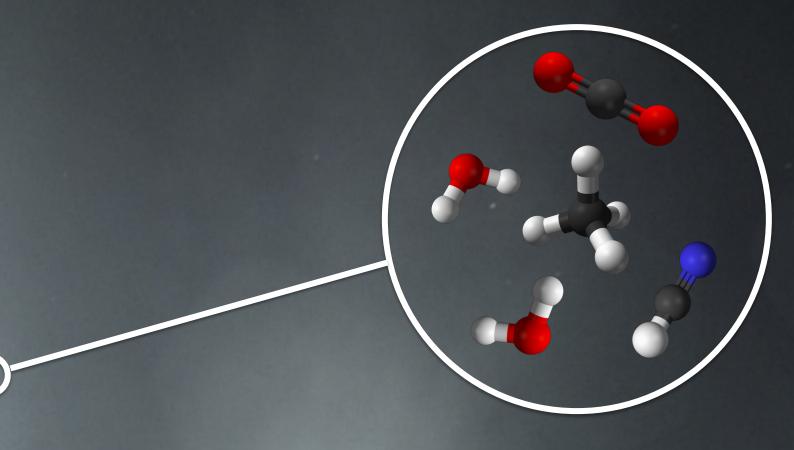












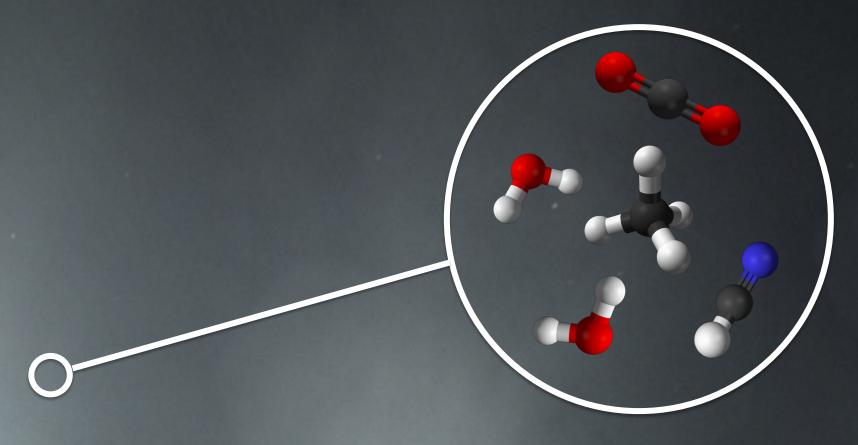
#### Plume gas

- Water, carbon dioxide, methane, ammonia, molecular hydrogen (H<sub>2</sub>)
- Simple and complex organic molecules



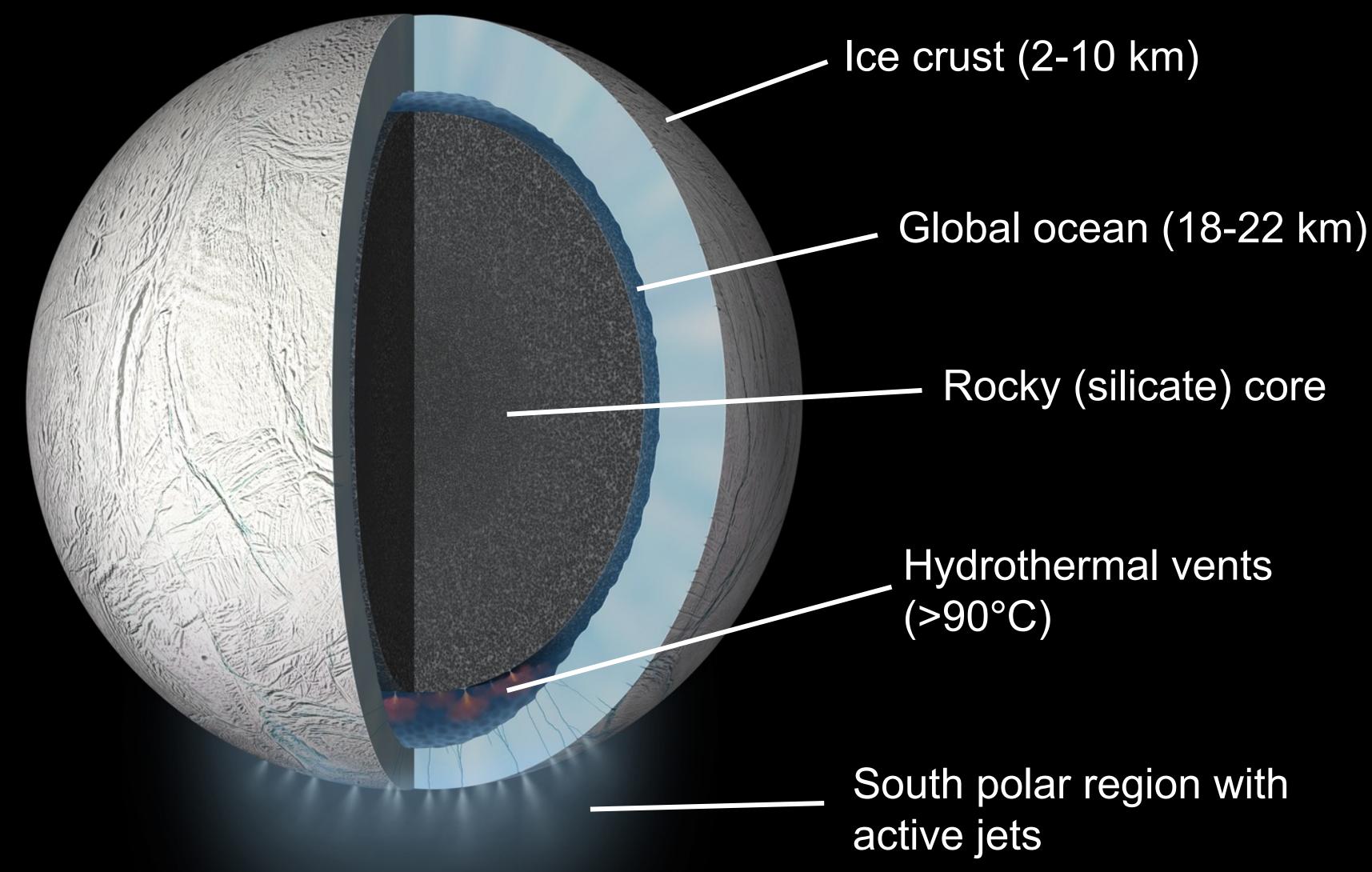
#### Plume grains

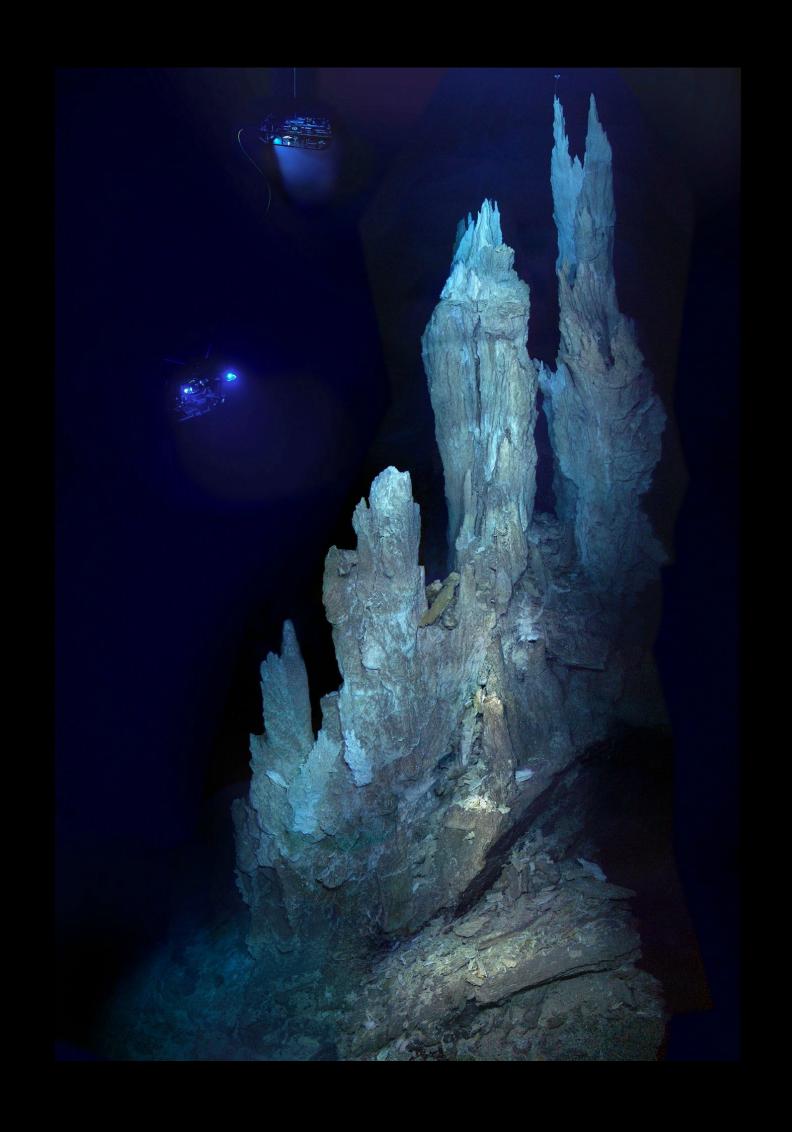
- Water ice, sodium chloride (like our oceans)
- Large organic molecules

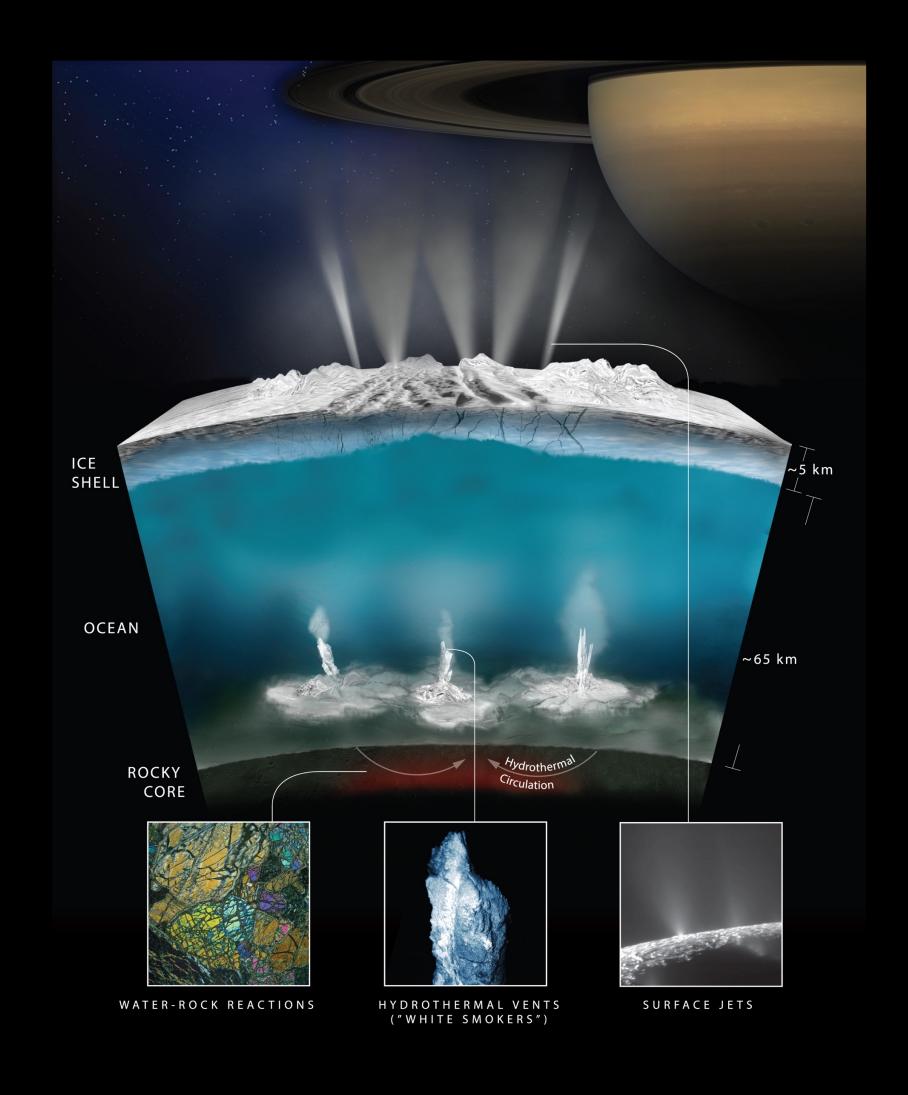


#### Plume gas

- Water, carbon dioxide, methane, ammonia, molecular hydrogen (H<sub>2</sub>)
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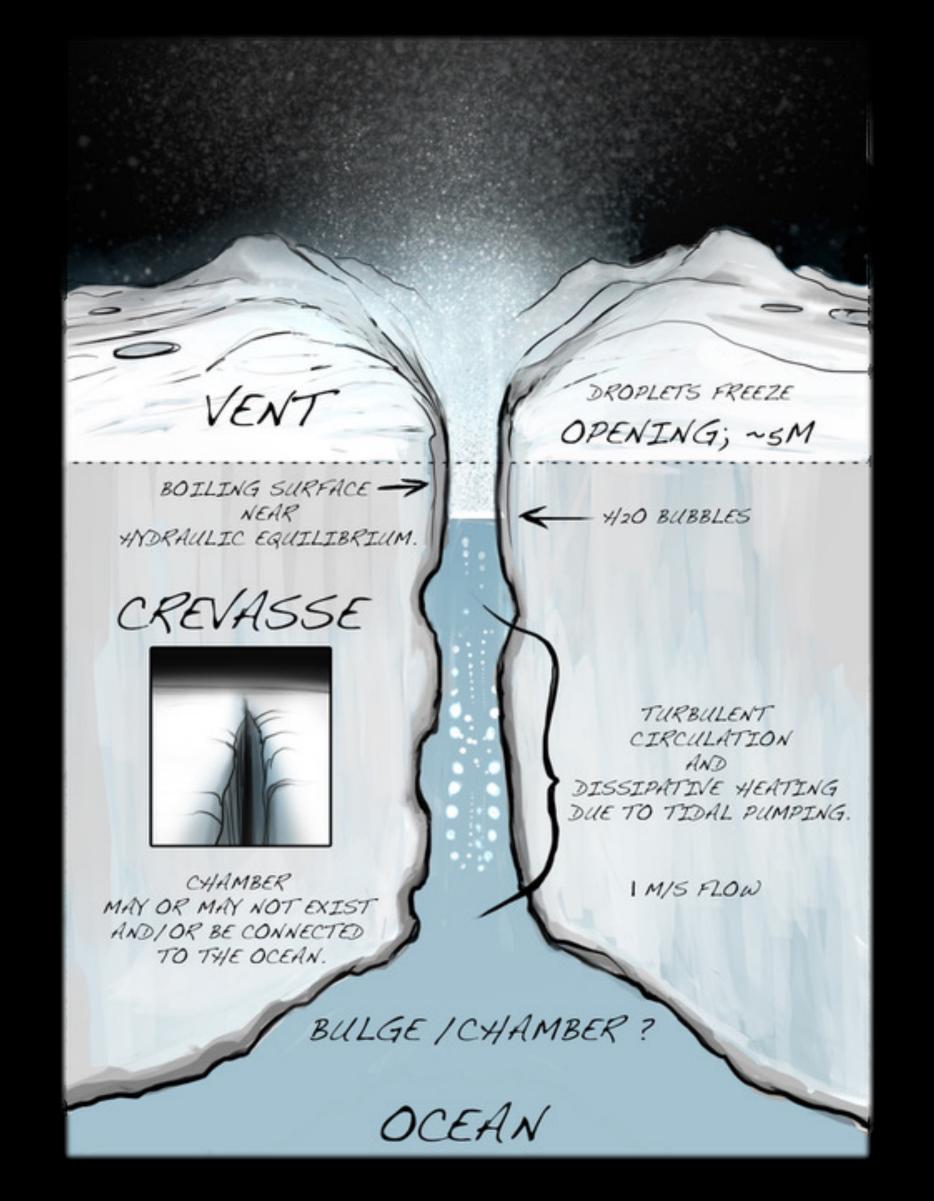


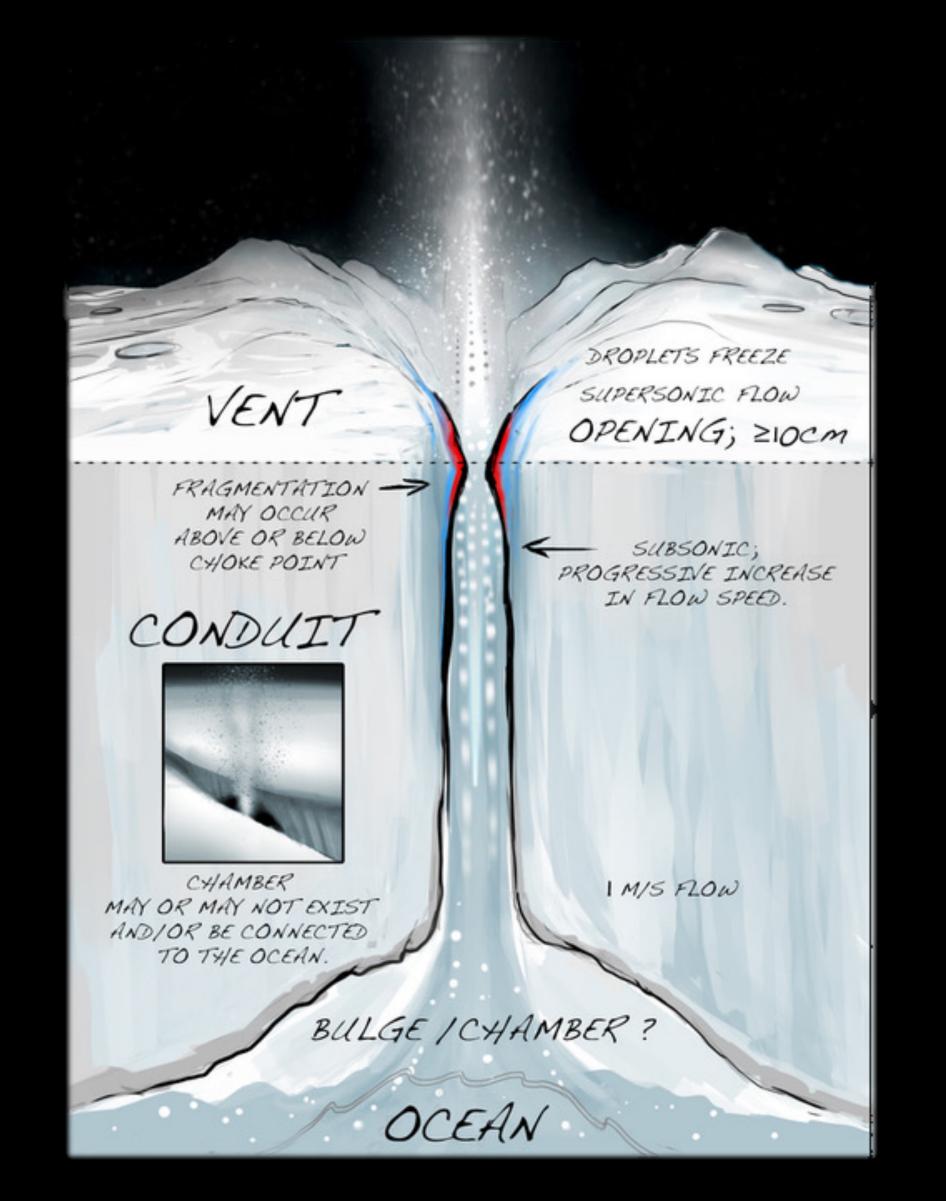


#### Concept Science Return

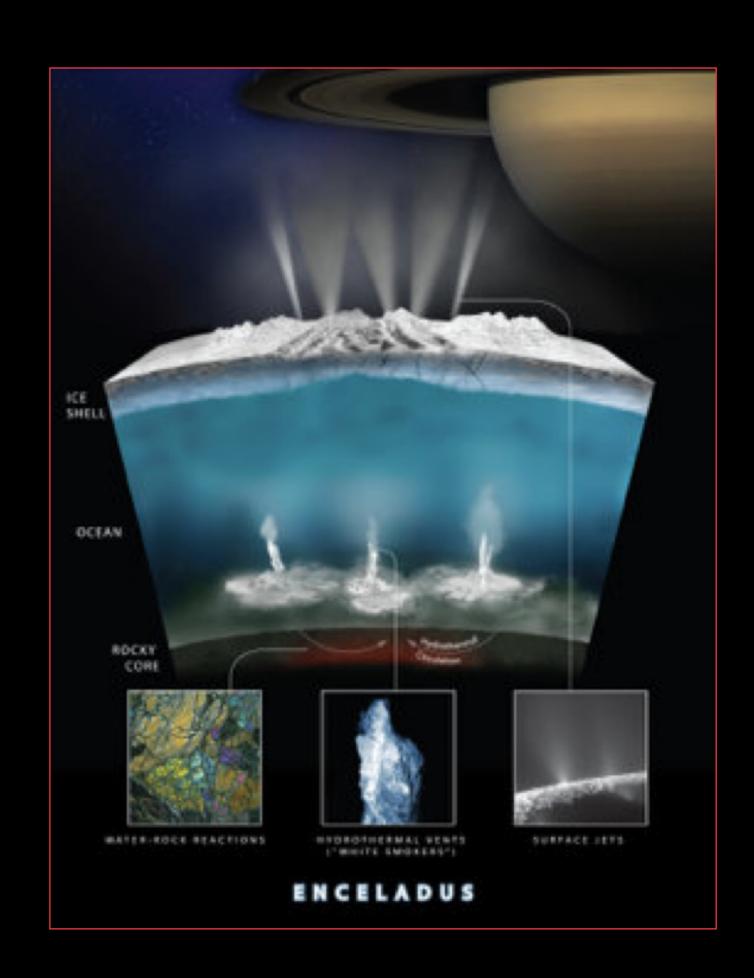
	Science Goal	Science Objective	Measurement Objective
iology	at Enceladus.	Detect and characterize organic indicators of extinct or extant life.	Quantify amino acids relative to glycine to establish biotic vs abiotic ratio, and determine their chirality.
			Quantify fatty acids relative to C12 (dodecanoic acid) to search for even/odd or other pattern different from Fischer-Tropsch synthesis.
d			Determine <sup>13</sup> C/ <sup>12</sup> C and D/H ratios in various alkanes to search for evidence of biological synthesis.
As			Quantify the amount of ATP present as an indicator of microbial activity.
		Detect any morphological indicators of life.	Identify any cells via imaging, composition and/or motility.
			Search for microbial mats, biofilms or biominerals.
tability	Assess the habitability of the Enceladus	Determine the physical characteristics of the Enceladus ocean.	Measure ocean temperature, specific conductivity, and turbidity.
Habita		Determine the chemical	Measure salts and volatiles to determine ocean pH and redox potential.
На			Search for energy sources available for life (redox pairs for chemosynthesis, dissolved volatiles, etc.)
olo	Characterize the internal structure	Determine ice shell thickness and depth of ocean.	Measure acoustic signals of reflecting body waves using geophone or seismometer.
		Determine vent eruption mechanism.	Measure changes in vent opening and gas/particle flux with orbital period.

#### Concept Why Reach the Ocean?





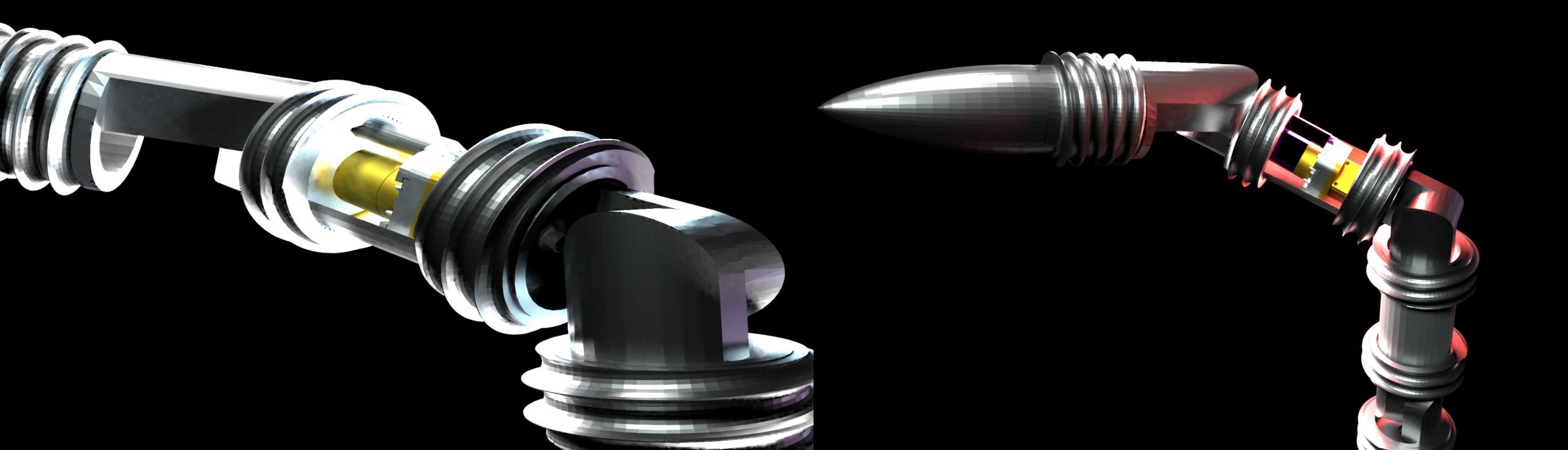
### **Concept Envelope of Critical Parameters**



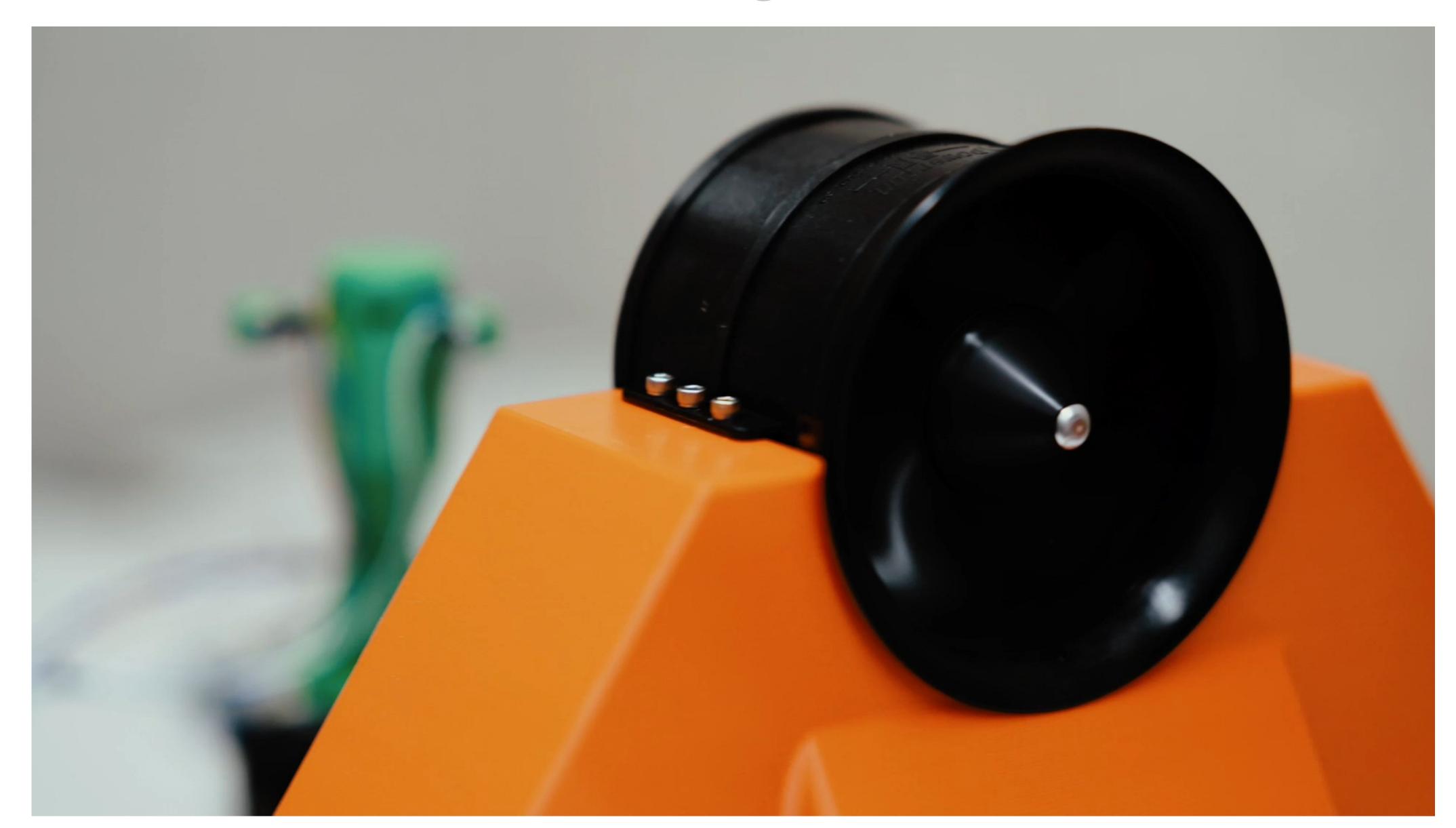
	Source	Envelope
Mass flux	Cassini	250 Kg/s (Tidal dependent)
Exit Velocity	Cassini	240-1000 m/s (Height independent of tides)
# of vents	Debated	>100
Dynamic pressure	Debated	~0 Pa
Ice Thickness	Cassini/ Debated	2-30 km
Shape	Debated	Fissure vs point sources
Plume throat	Debated	2 mm - 140 mm (Low end is likely implausible due to heat balance, >70 mm likely)
Particle size	Cassini	<100 micron
Vent static pressure	Debated	~0 kPa-9E <sup>5</sup> kPa

#### Instrument Technology Investments

- Front end. We need access to ocean liquid and plume grains. Some kind of liquid 'sipper' is needed, in addition to a plume grain collector.
- Concentrator. Depending on biosignature targets, sample concentration may be needed to achieve required limits of detection for trace species.



#### Technical Goals Flow Sensing

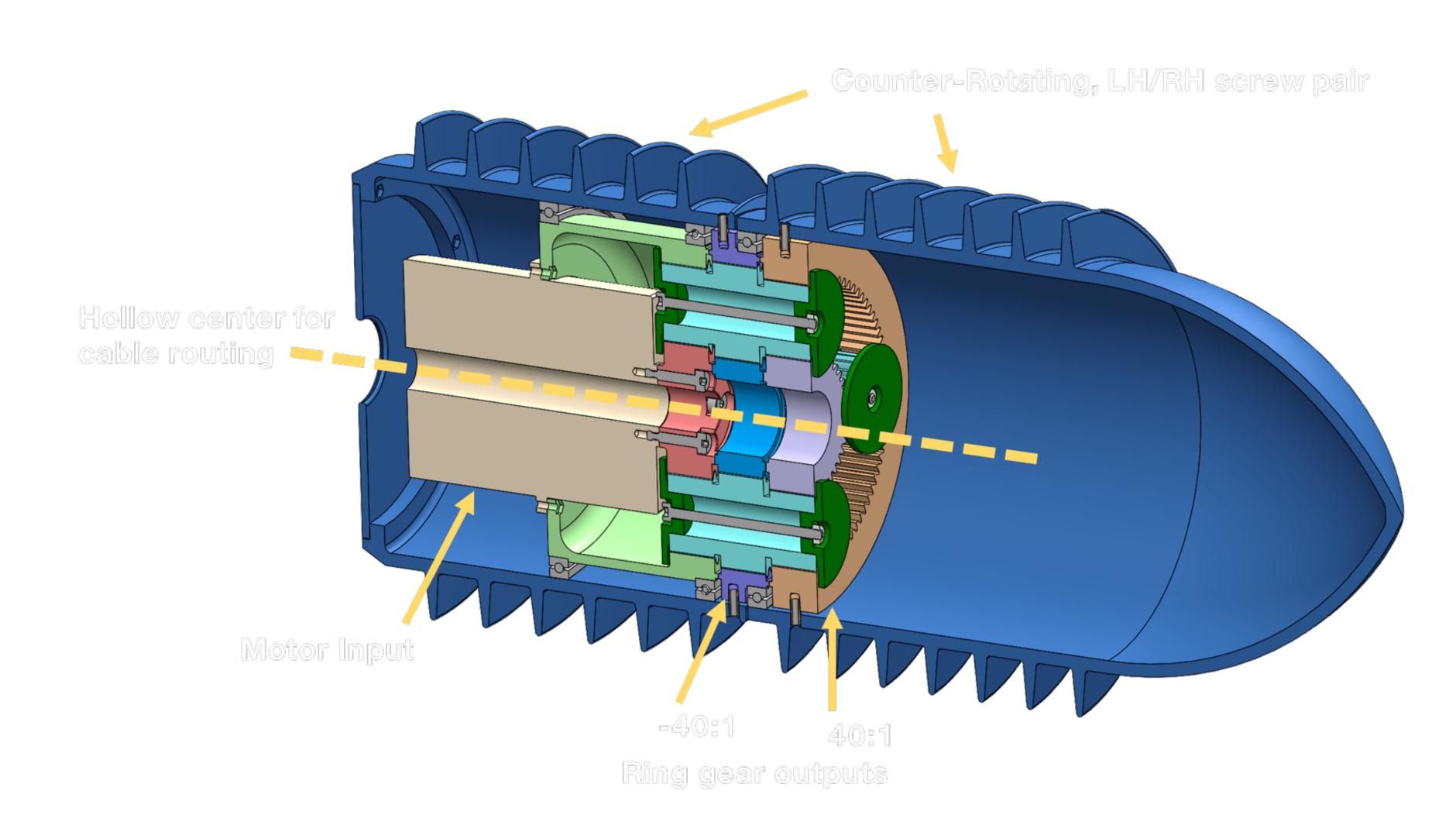


#### Technical Goals Adaptive Force Control



#### Technical Goals Actuators & Gears

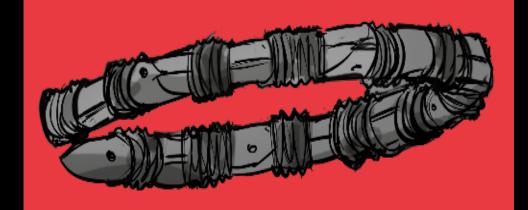
EELS Actuator and Screw Mobility Prototype Integrating Highly Compact, Torque-Dense Bearlingless Planetary Gearbox



#### **Autonomy Challenge Rate of Traverse**

M2020 MARS YEARS: 1.25 DISTANCE TO COVER: 15 km SAMPLES TO COLLECT: 20 drilled samples

EELS



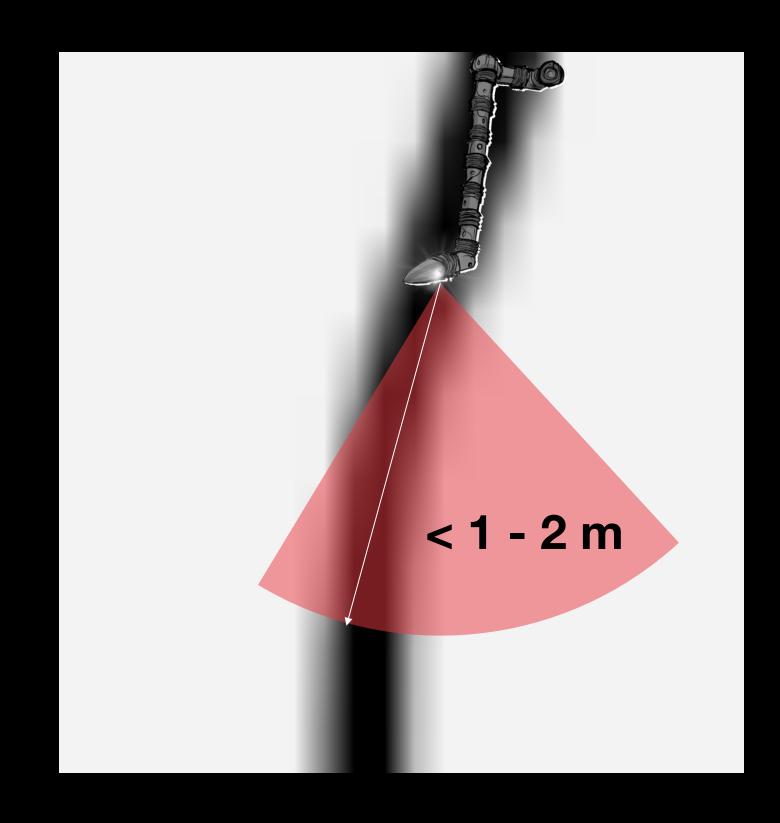
**Earth hours** 

16
Distance to cover:
Up to
3 km

Vertically

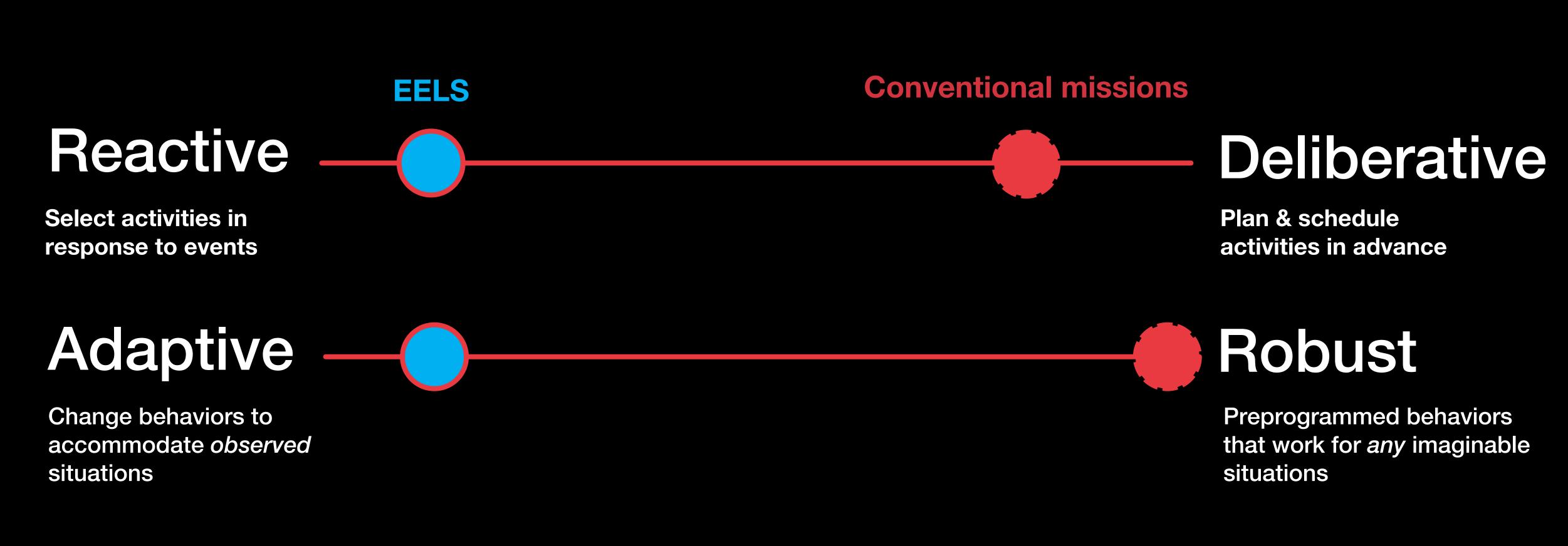
#### **Autonomy Challenge Visibility**





Interior of Old Faithful
J. Westphal, S. Sieffer, R. Hutchinson (1993)

#### **EELS Autonomy Principles**



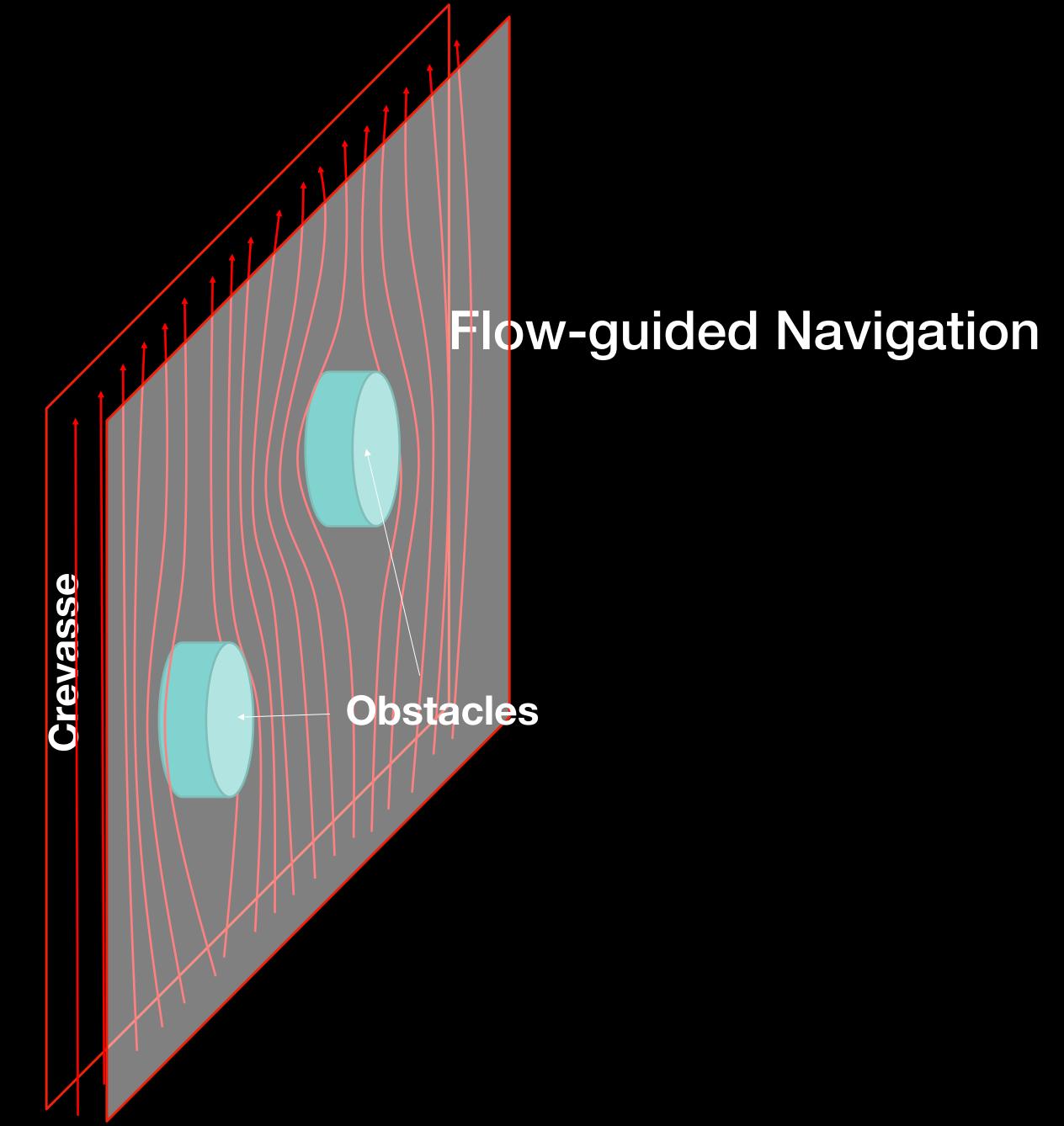
#### Resilient

Keep going with remaining capabilities



Stop activities, go into safe mode, and wait for the ground

#### Flow-guided Navigation

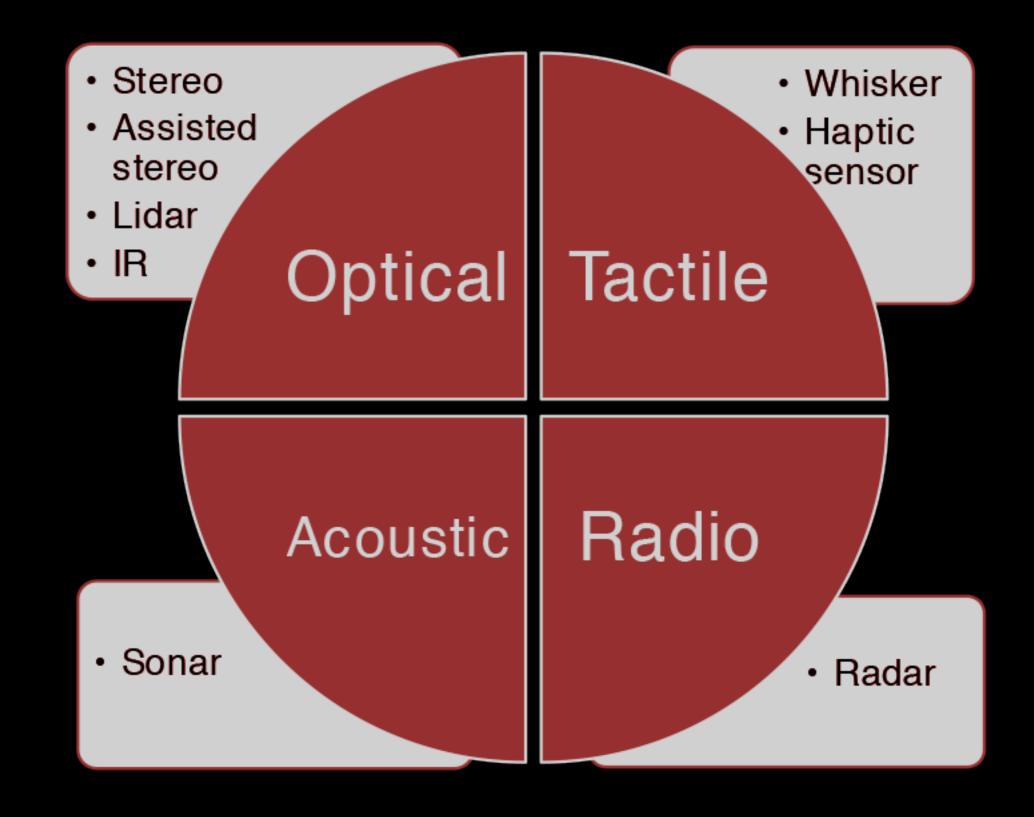


#### Adaptive gait control



Shape-based admittance control

#### Resilient perception with sensor fusion

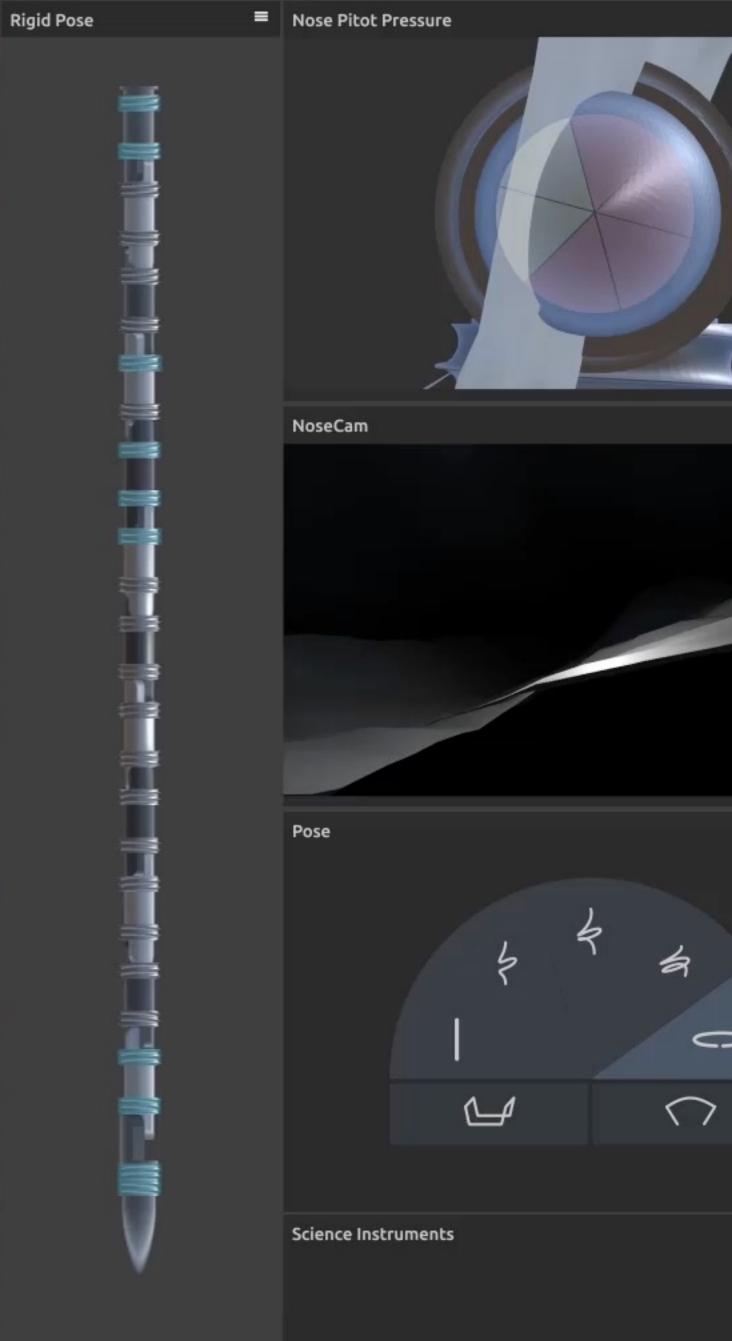




De-rain/de-haze Movie by S. Narasimhan, CMU







O0:05:00

EEL 

Pose Change

NoseCam Capture

Pitot Flowspeed

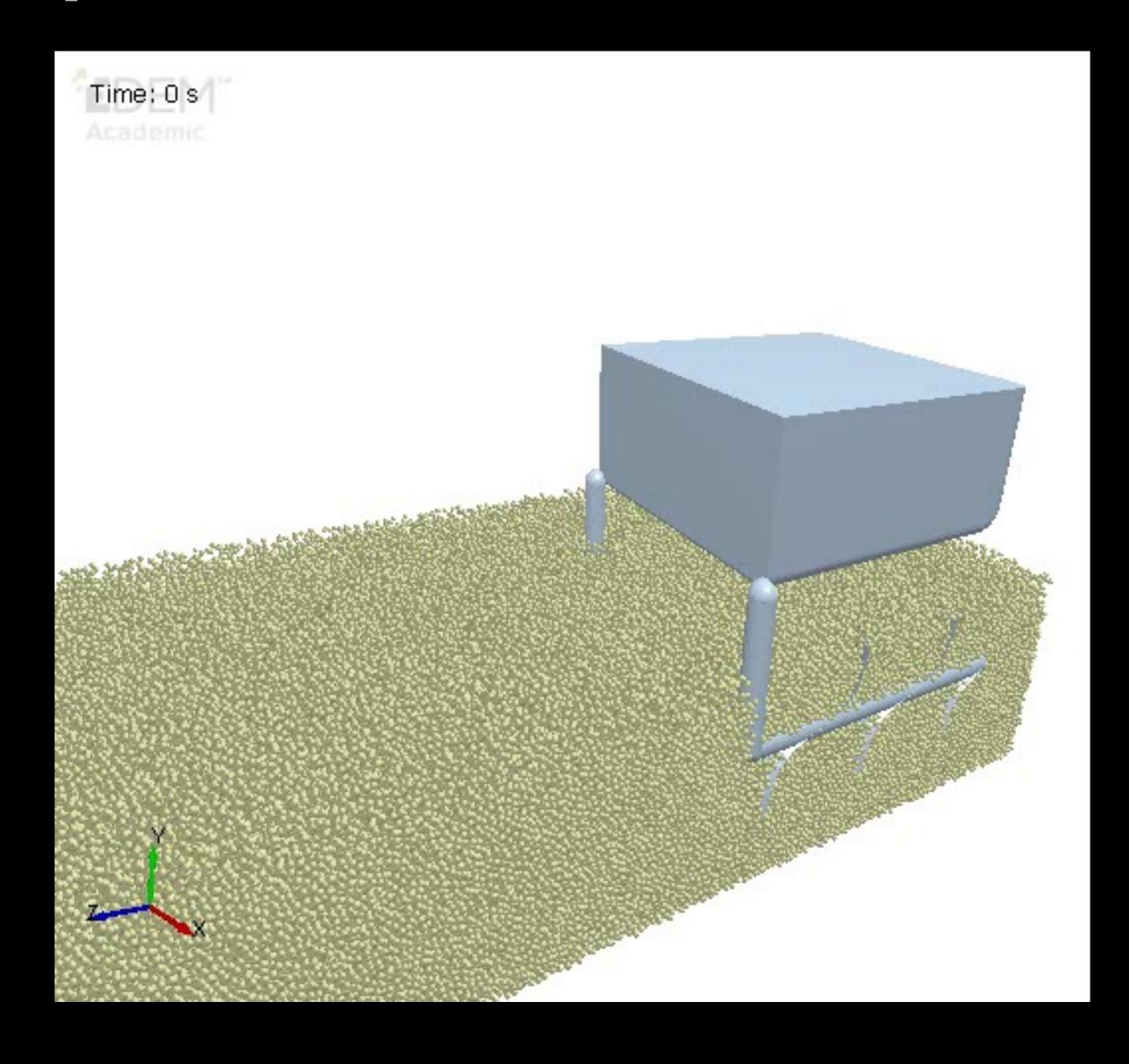
Tether Tension

Temp °C

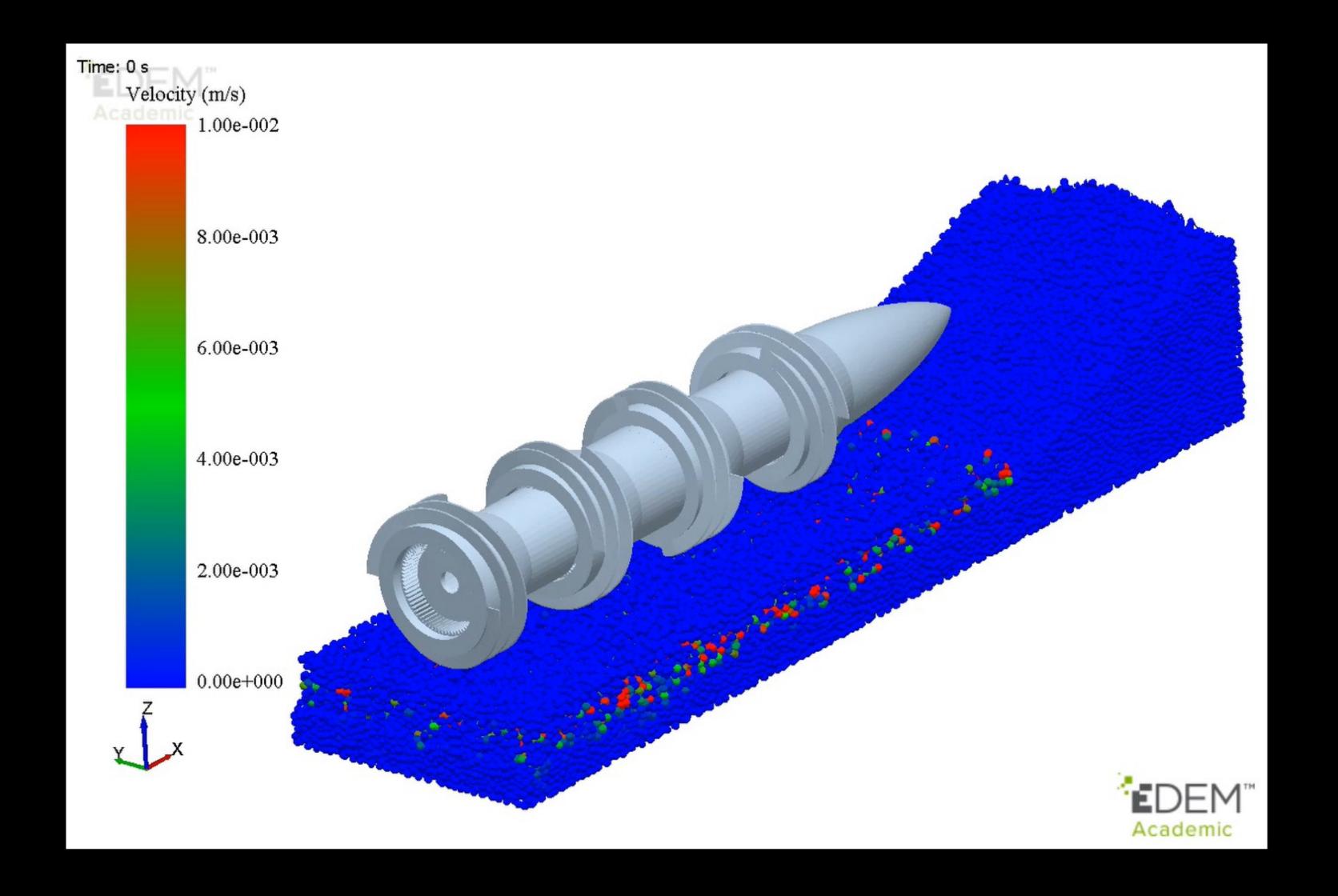
IMU

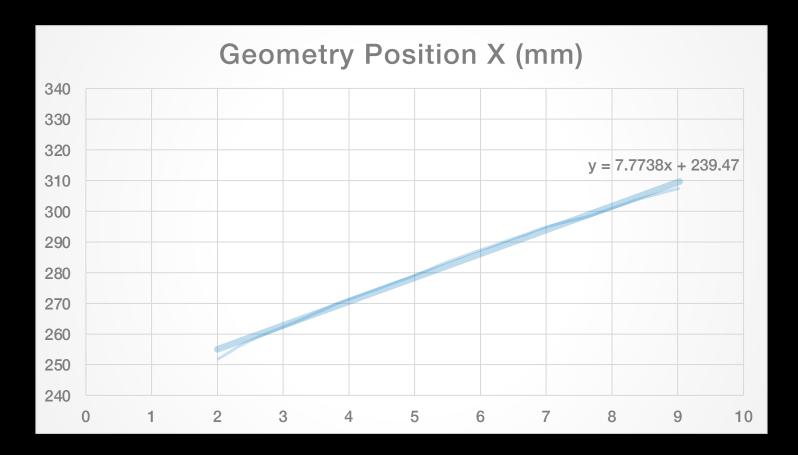
#### Technical Goals Screw Propulsion

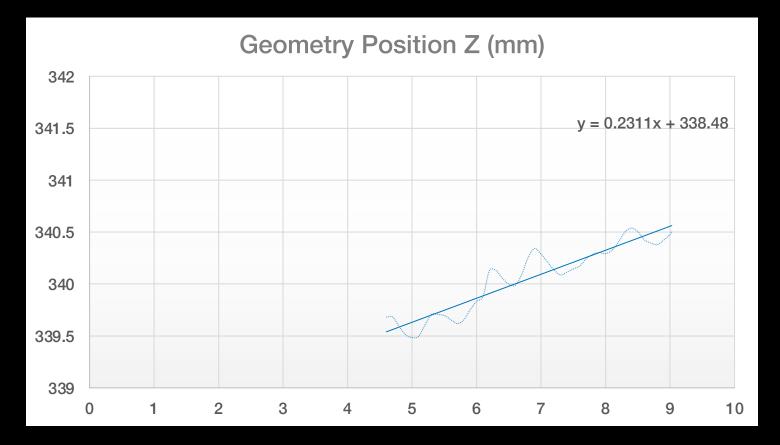
- Screw Propulsion has been proposed for amphibious, icy environments previously including the ZIL-2906 and GPI-72 (Koshurina)
- Modern developments to revive this form for rescue and resource exploration on the Arctic shelf have shown promise (Abramova)
- One difficulty in applying the traditional, counter-rotating dual screw design in a low gravity environment is the instability of a high center of mass (see video)
- Solution is to locate the majority of mass inline with propulsive vector, creating more inherent stability (EELS)

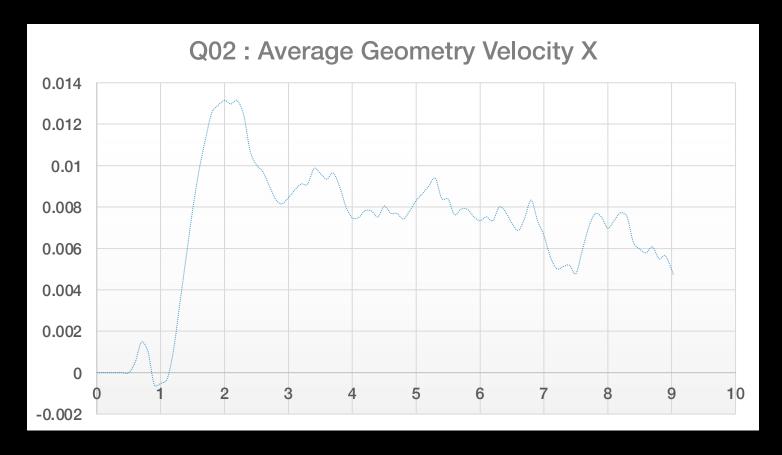


#### Technical Goals Mobility Simulation

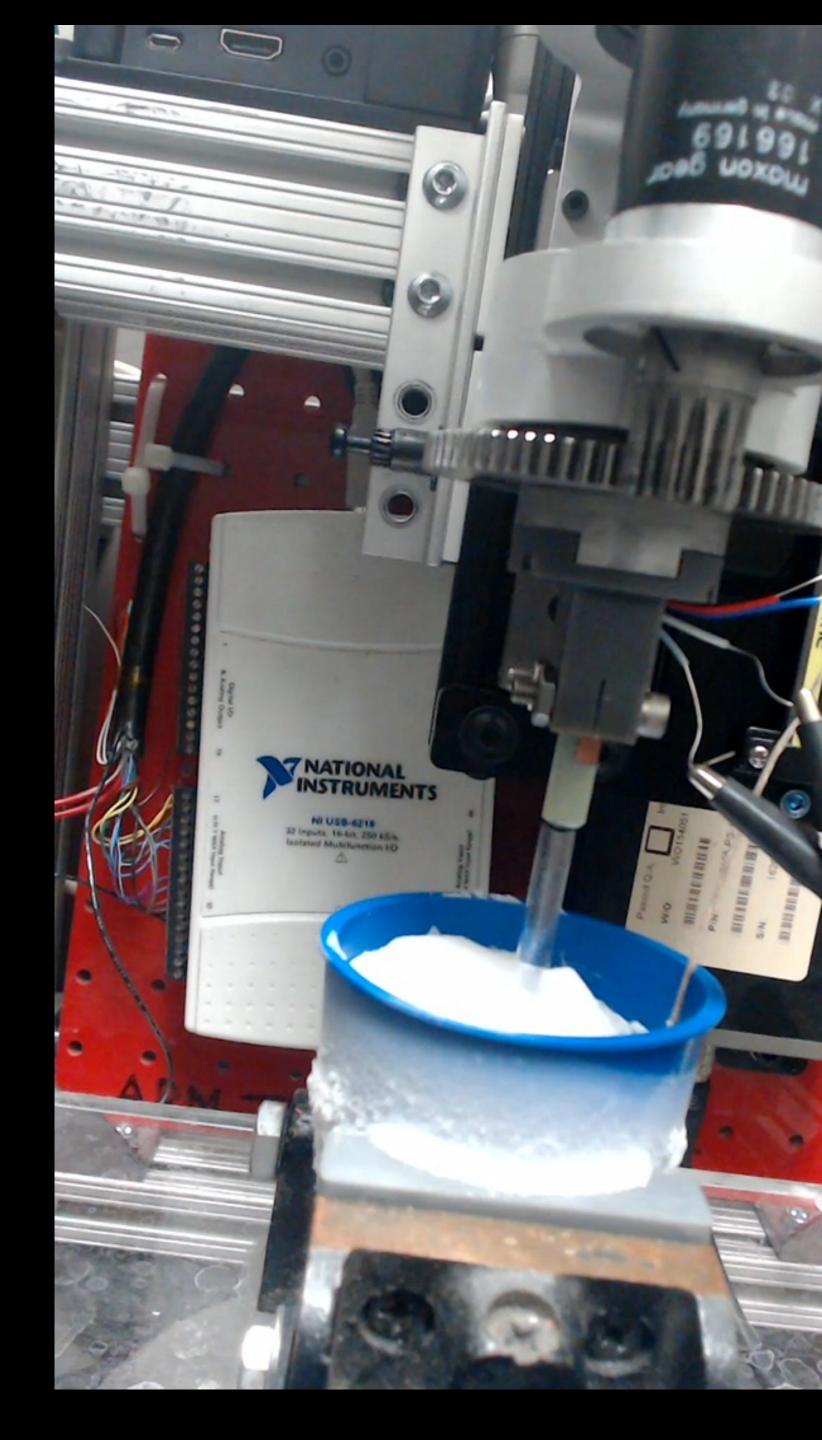








#### Technical Goals Ice Anchoring



## Thermal-Inertial Odometry for Autonomous Flight Throughout the Night

Jeff Delaune, Robert Hewitt, Daniel Lytle, Cristina Sorice, Rohan Thakker, and Larry Matthies



#### Technical Goals Determine Greatest Mass Flux





**Artists Concept** 

